



Centrum Wiskunde & Informatica



Universiteit  
Leiden

# Ultra-fast reconstruction using Fourier domain filters

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6 July 2020

SIAM Imaging Science



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Mitigate the influence of less accurate but fast backprojection operators

# Introduction

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# Iterative reconstruction

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+ Robust w.r.t. noise and limited angular range

- Computationally expensive

# Iterative reconstruction

$$\begin{aligned} \mathbf{x}^{(k+1)} &= \underbrace{(\mathbf{1} - \mathbf{C}\mathbf{W}^T\mathbf{R}\mathbf{W})}_A \mathbf{x}^{(k)} + \underbrace{\mathbf{C}\mathbf{W}^T\mathbf{R}}_B \mathbf{p} \\ &= \begin{pmatrix} \mathbf{1} & \mathbf{0} \end{pmatrix} \begin{pmatrix} A & B \\ \mathbf{0} & \mathbf{1} \end{pmatrix}^k \begin{pmatrix} \mathbf{0} \\ \mathbf{p} \end{pmatrix} \end{aligned}$$

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Can we approximate iterative reconstruction results with *faster* analytical methods?



## Algebraic filters

---

An analytical method  $\mathcal{A}$  such as filtered backprojection (FBP) can be written as

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We can optimise this filter by solving an optimisation problem similar to that in iterative methods

$$\begin{aligned}\mathbf{h}^* &= \arg \min_{\mathbf{h}} \|\mathbf{p} - \mathbf{W}\mathcal{A}(\mathbf{h}, \mathbf{p})\|_2^2 \\ \mathbf{h}^* &= \arg \min_{\mathbf{h}} \|\mathbf{p} - \mathbf{W}\mathbf{W}_{\mathcal{A}}^T \mathbf{C}_p \mathbf{h}\|_2^2\end{aligned}\tag{4}$$

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$\mathbf{h}^*$  is the **minimum-residual** filter

# Advantages

Typical size of projection data is  $N_\theta N_d \sim 10^6$

Reconstruction volume size is  $N^2 \sim 10^6$

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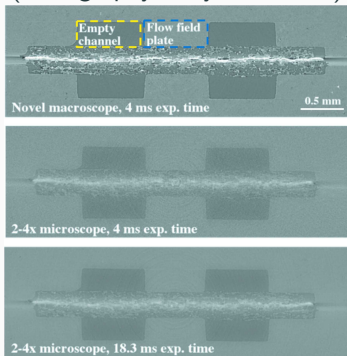
Reconstruction volume size is  $N^2 \sim 10^6$

- Filter size is  $N_d \sim 10^3$
- Filter dimension can be further reduced to  $\mathcal{O}(\log N_d)$
- Filter can be reused for similar noise experimental geometries and noise statistics



# High-throughput applications

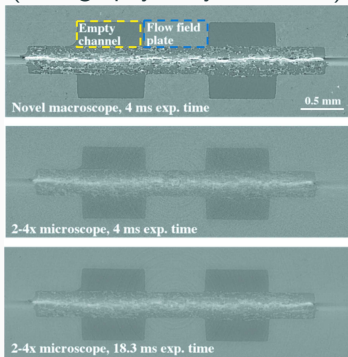
Time-resolved experiments  
(tomography at synchrotrons)



Reconstructions of a fuel cell  
(Bührer et al., 2019)

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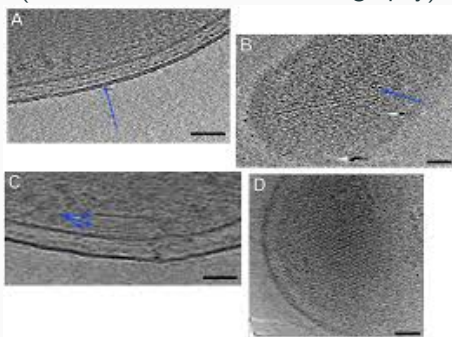
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Data rates  $\sim 10\text{GB s}^{-1} \rightarrow$

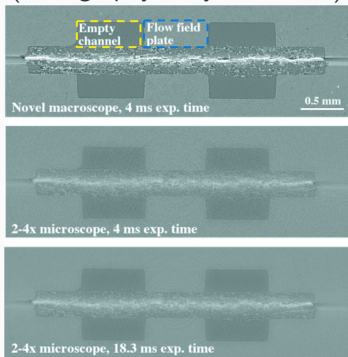
## Continuous acquisition (continuous-tilt electron tomography)



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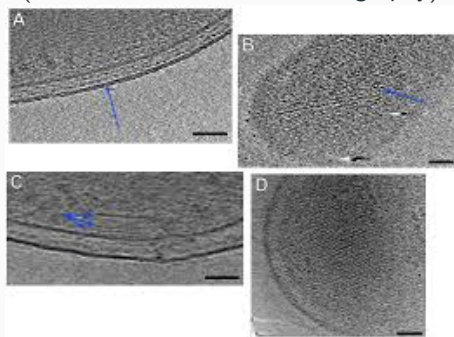
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Data rates  $\sim 10\text{GB s}^{-1} \rightarrow$  Can we make reconstructions even faster?

## Continuous acquisition (continuous-tilt electron tomography)

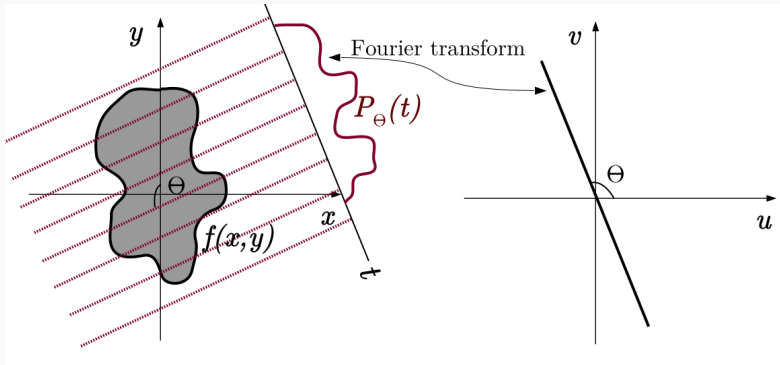


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# Fourier-domain filters

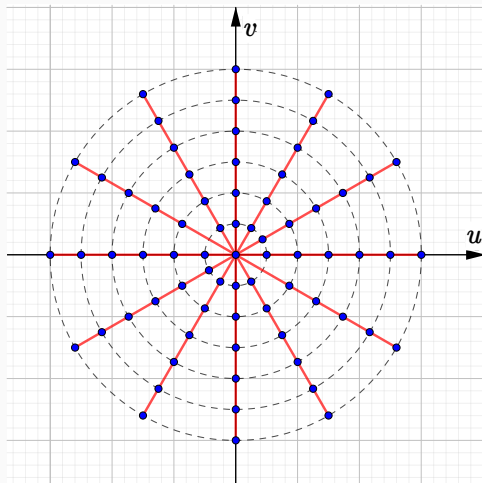
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# Fourier slice theorem



$$\tilde{P}_\theta(\omega) = \tilde{F}(\omega \cos \theta, \omega \sin \theta)$$

# Fourier slice theorem



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## Steps in Gridrec

- filtering in Fourier space



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- filtering in Fourier space
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FBP backprojection:  $\mathcal{O}(N^2 N_\theta)$

Gridrec 2D FFT:  $\mathcal{O}(N^2 \log N)$

# Fourier domain algorithms

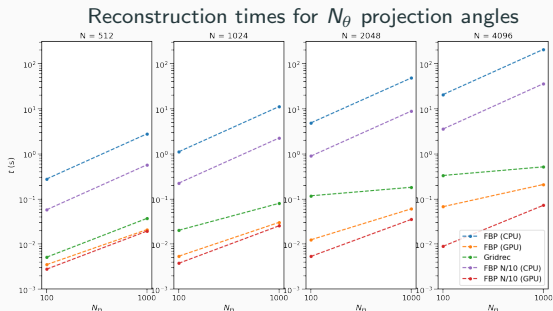
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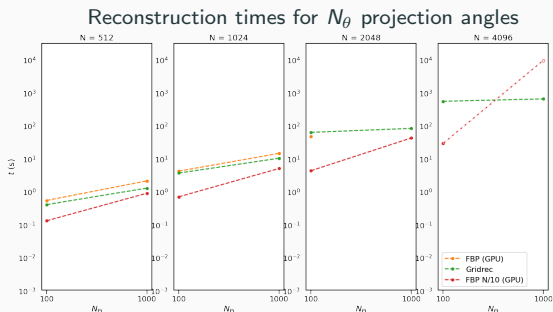
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$$\mathbf{h}^* = \arg \min_{\mathbf{h}} \|\mathbf{p} - \mathbf{W}\mathbf{W}^T \mathbf{C}_p \mathbf{h}\|_2^2$$

using projectors in Fourier domain



# Filter computation

- Compute minimum-residual filter

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using projectors in Fourier domain

- Speed up filter computation by expanding in suitable basis

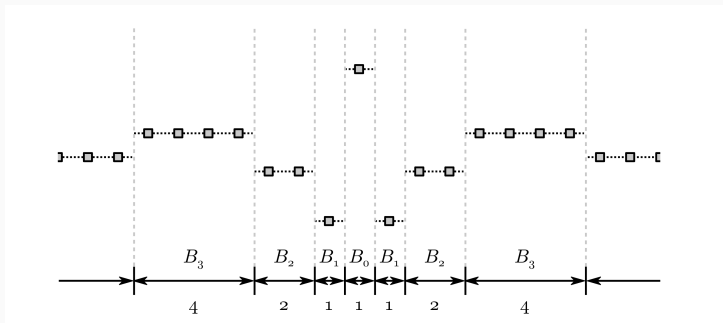
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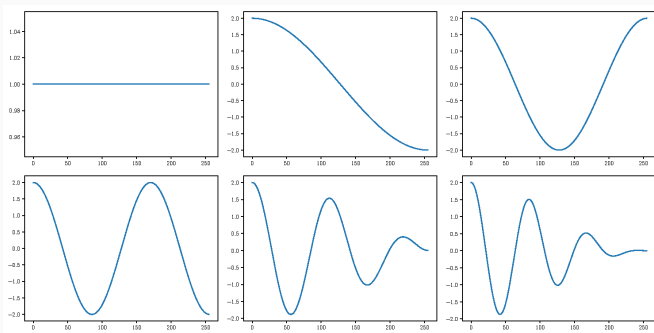
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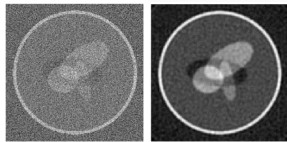
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# Results — 1: phantom

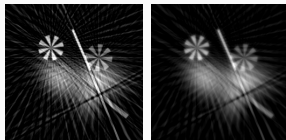
Noisy sinogram



ramp filter

our filter

Sinogram with few angles

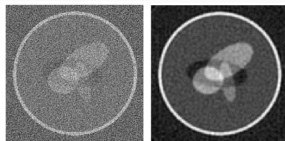


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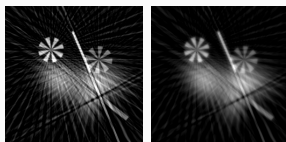
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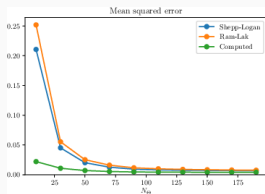
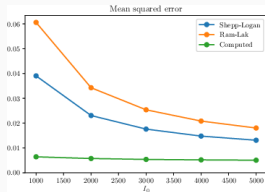
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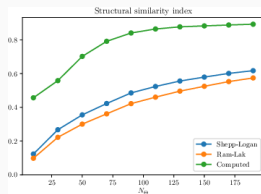
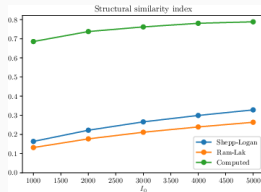
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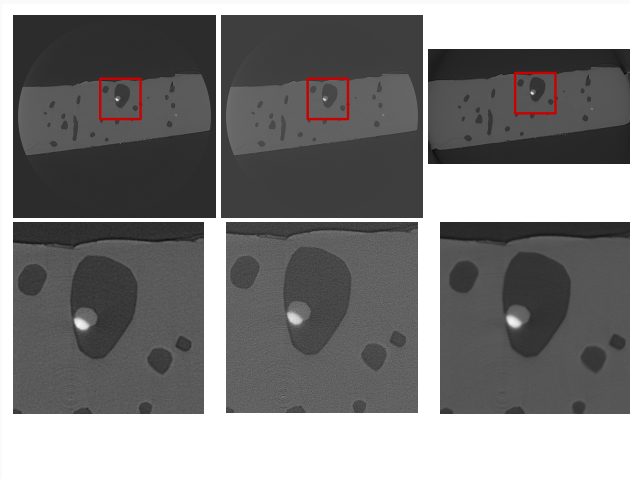
Mean squared error



Structural similarity



## Results — 2: synchrotron data



(left to right) Gridrec reconstructions using a minimum-residual filter, the Parzen filter, and additional phase retrieval

# High performance implementations

- Different implementations of the same algorithm result in *quantitatively* different reconstructions

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→ Compute minimum-residual filters for standard implementations  
! Does not require knowledge of the implementation

## **Implementation-specific filters**

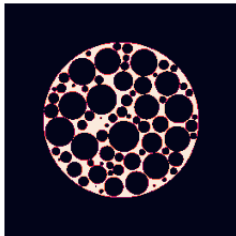
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Minimum-residual filters *reduce* the mismatch between operators

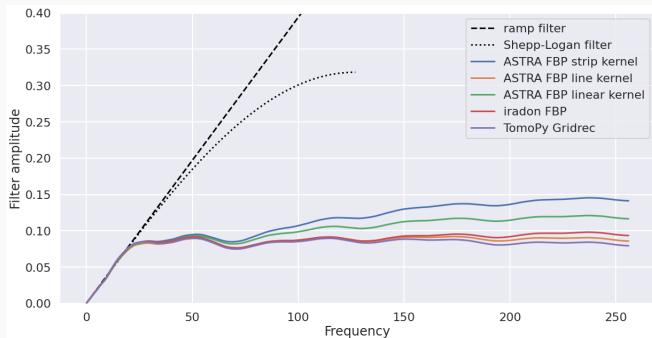
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Foam phantom



Minimum-residual filter shapes

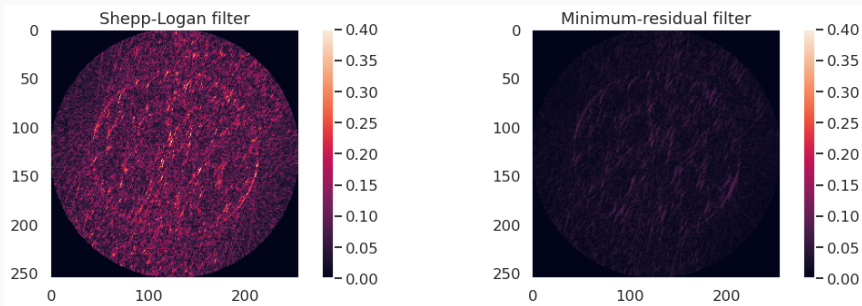
Pixelwise standard deviation in reconstructions

$$\text{std}\{\mathbf{x}_r^{\text{strip}}, \mathbf{x}_r^{\text{line}}, \mathbf{x}_r^{\text{linear}}, \mathbf{x}_r^{\text{iradon}}, \mathbf{x}_r^{\text{gridrec}}\}$$

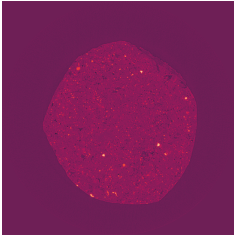


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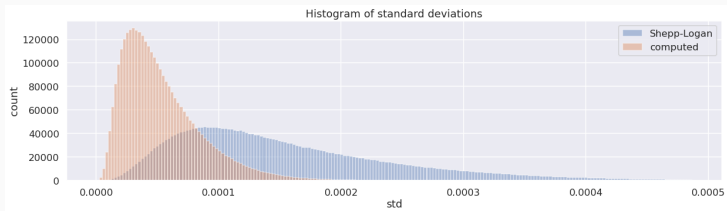
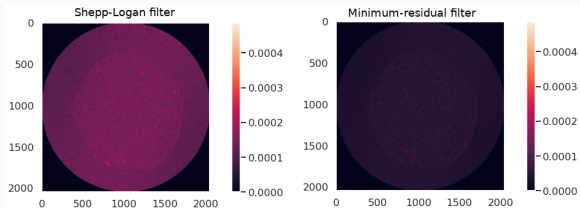
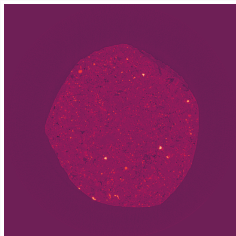
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Round-robin dataset from Tomobank



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# Conclusions

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## Summary and outlook

- Analytical algorithms despite their inability to handle imperfect data are **widely used** in practice because they are **fast**
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- Learn filter by optimising to more than one dataset
- More general approach for learning corrections to the backprojection operator from data

**Thank you for your attention!**